

# Properties of the electromagnetic softening and hardening spring: experiment and simulation

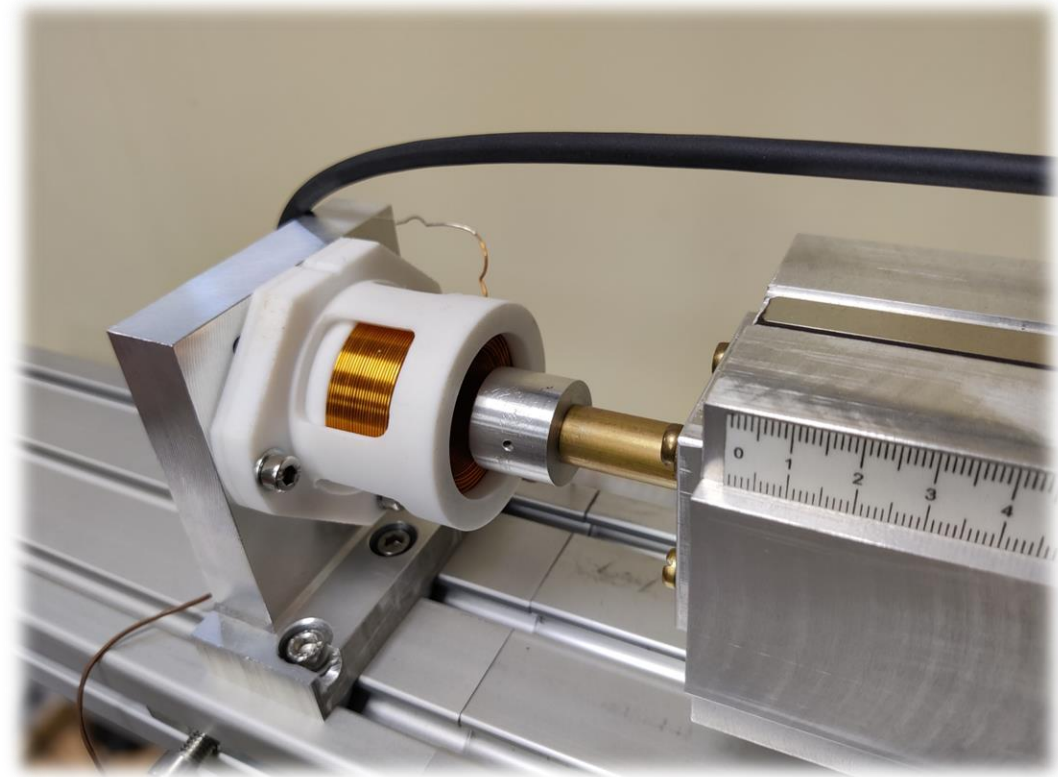
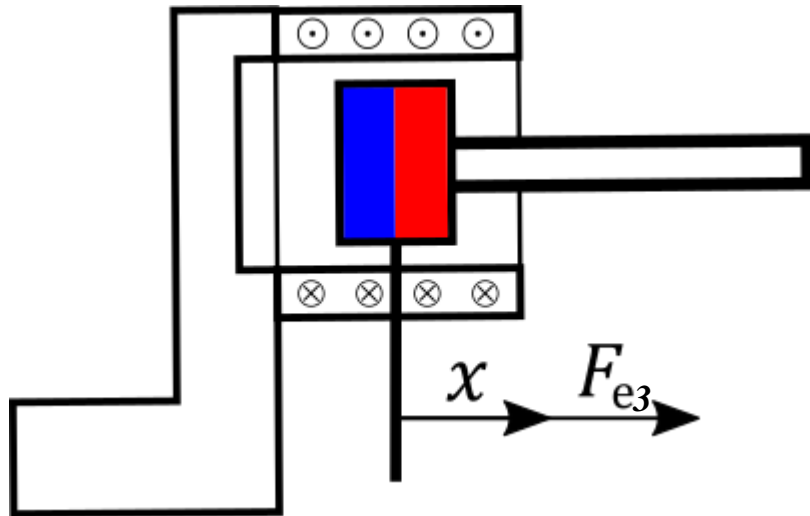
Maksymilian Bednarek



14.05.2024

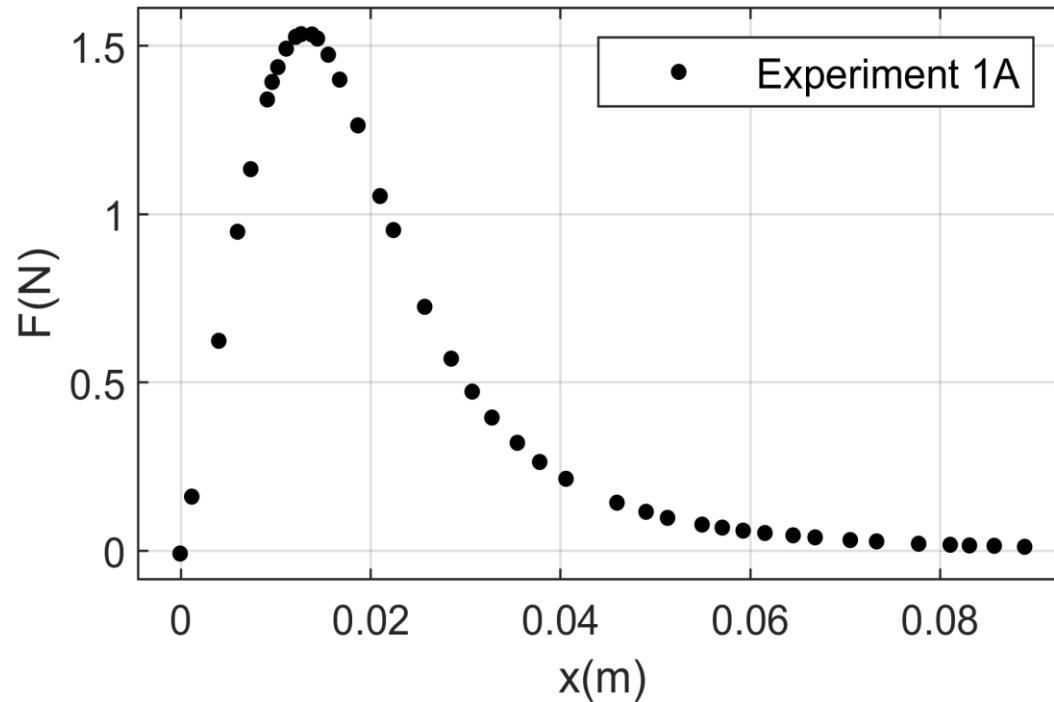
# Electromagnetic spring

What is an electromagnetic spring ?



# Electromagnetic spring

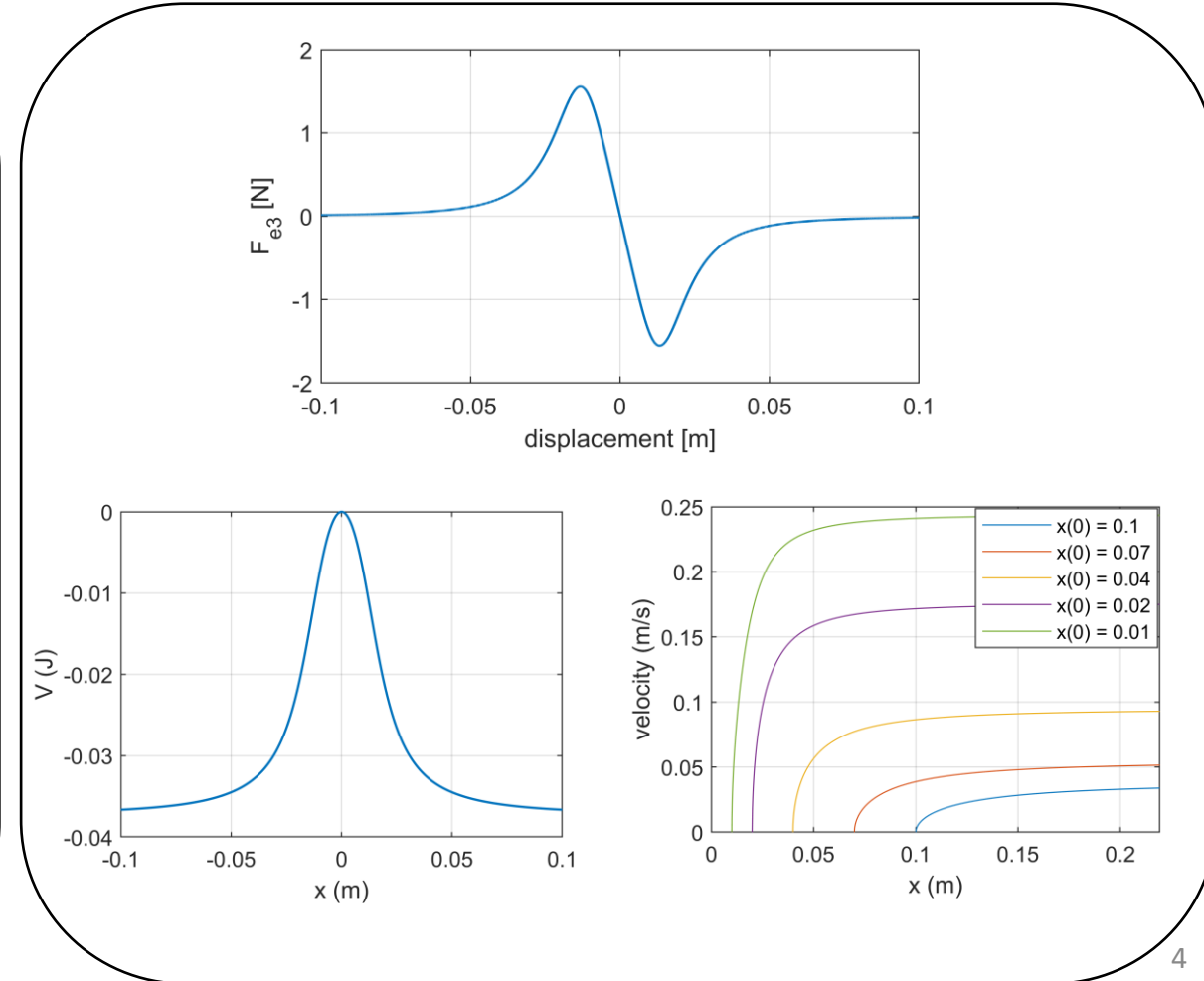
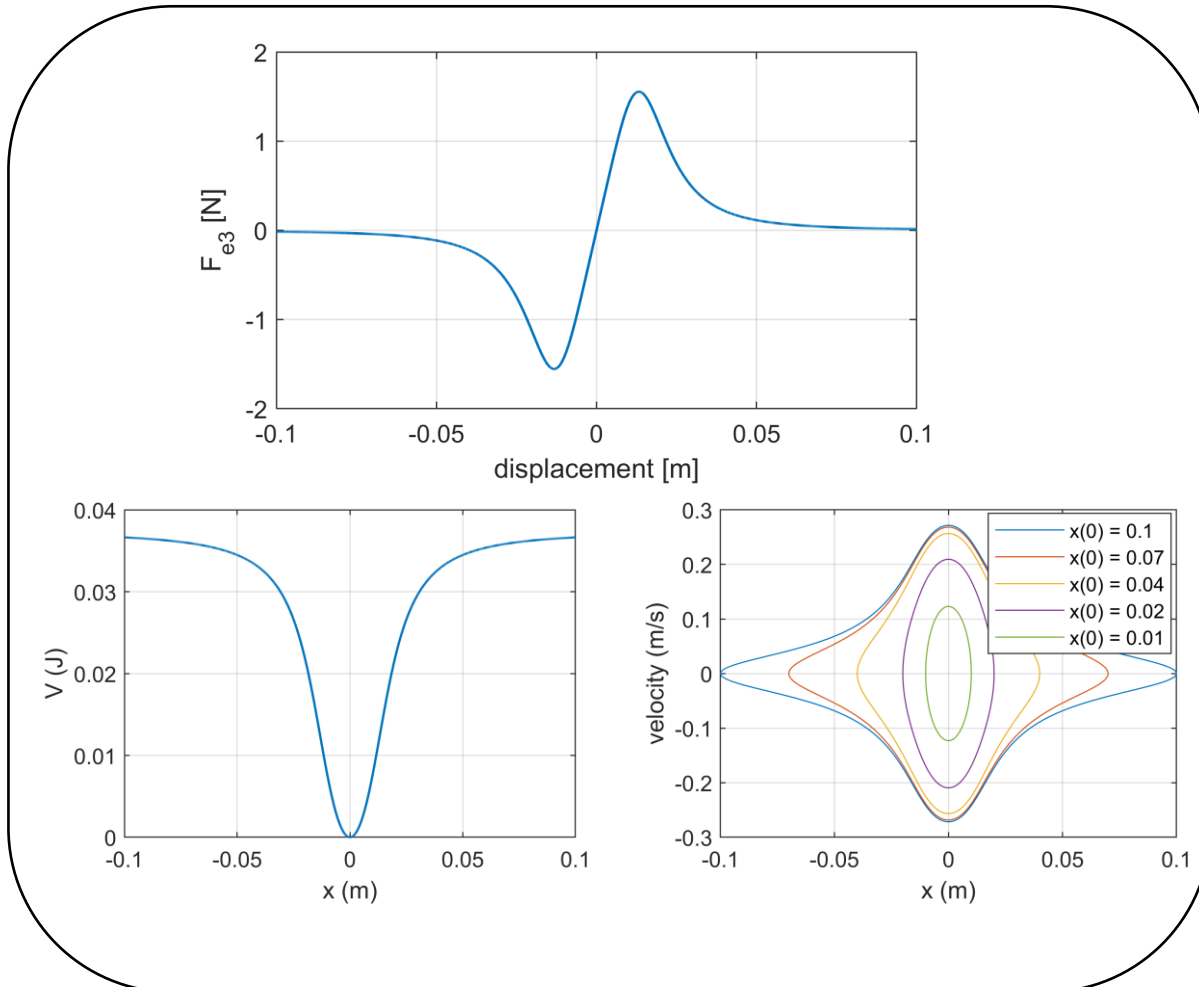
How to mathematically describe the force?



$$F_{e3} = \frac{pIq^3x}{q^4 + x^4}$$

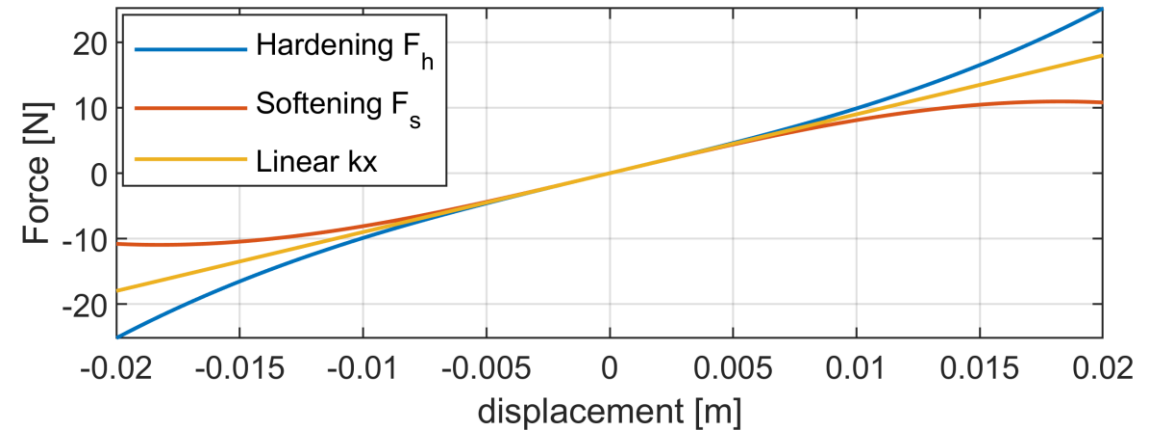
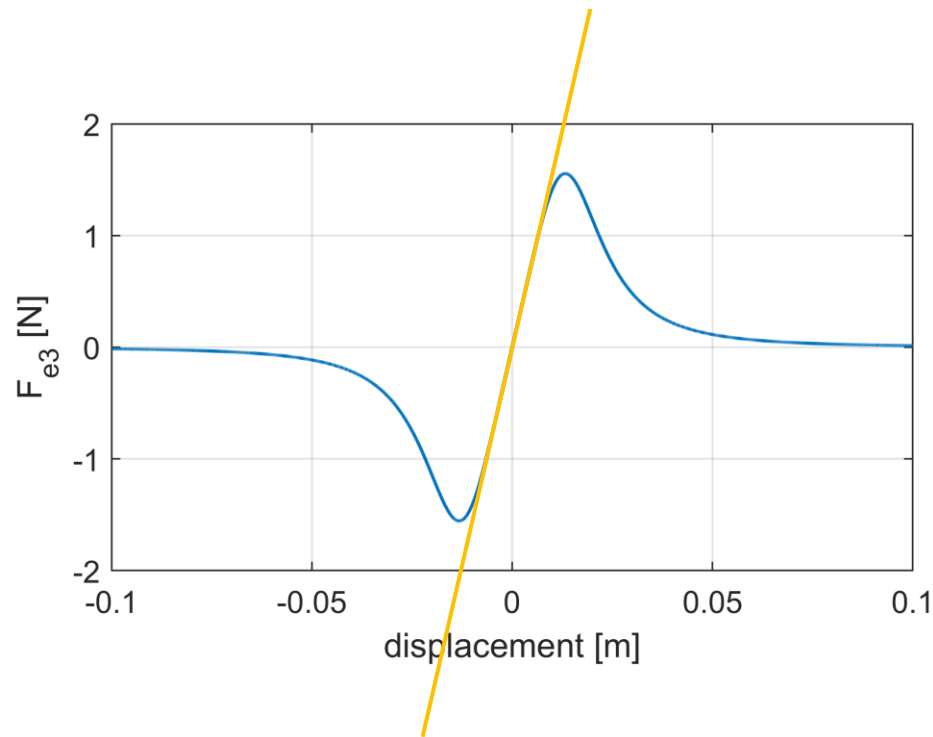
# Electromagnetic spring

## Polarity of the flowing current



# Nonlinearity in springs

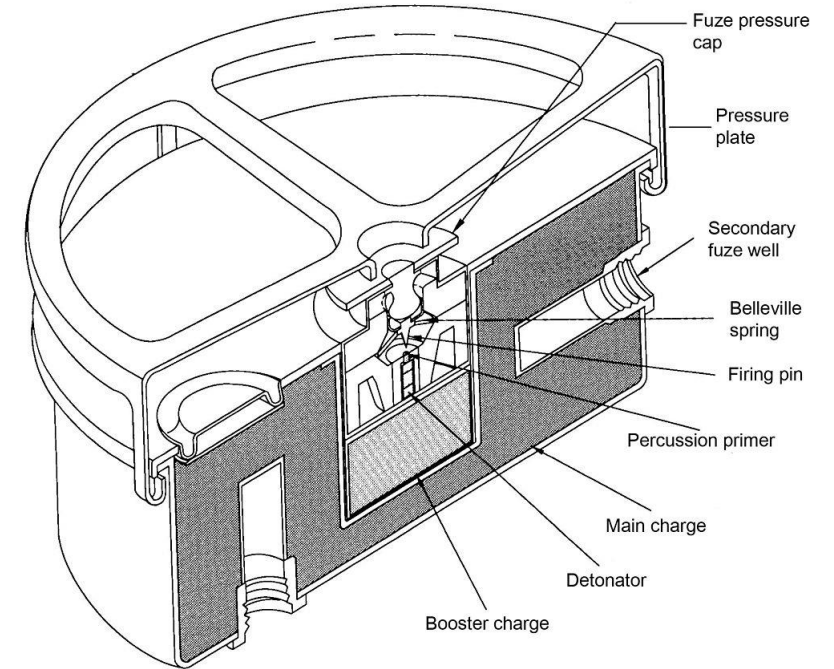
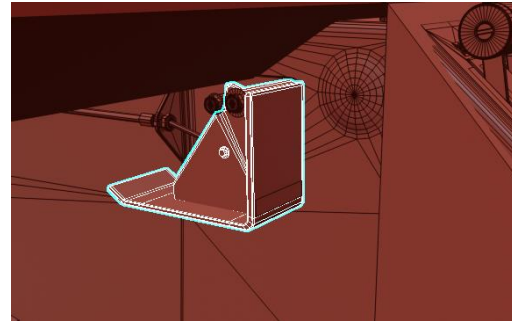
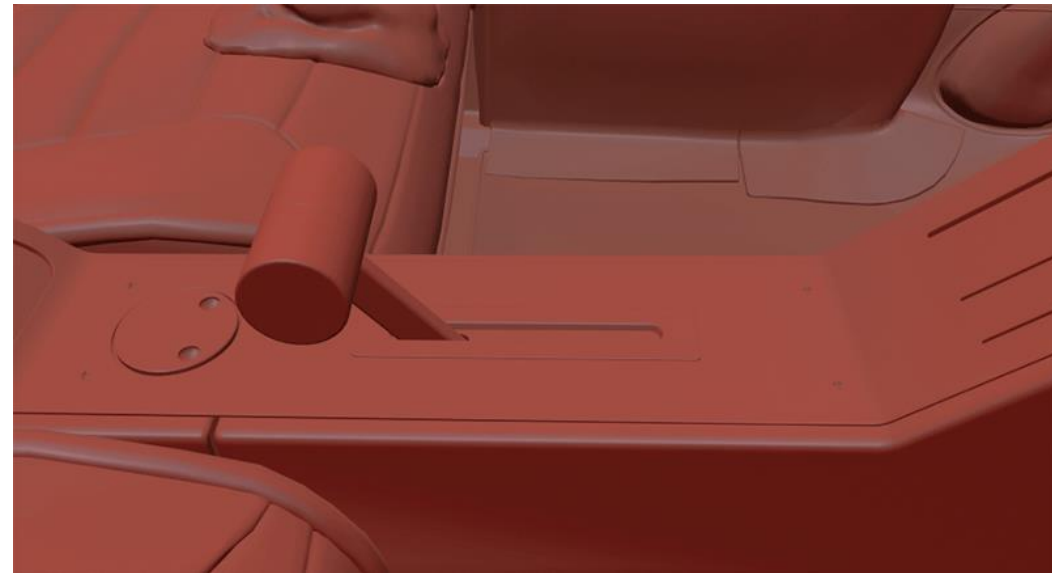
## Softening and hardening characteristic



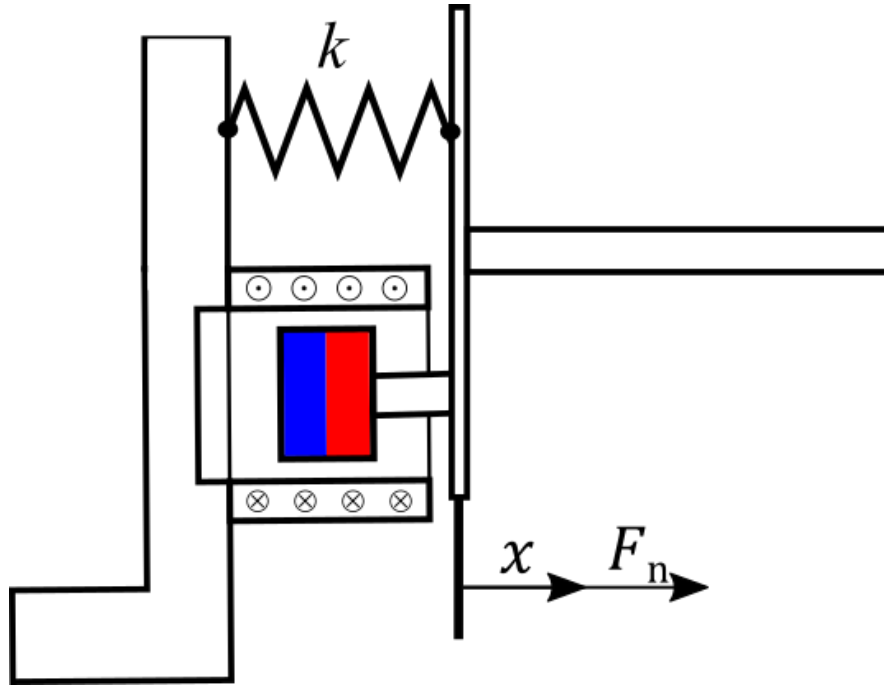
Hardening springs are such kind of nonlinear springs in which the force increases more rapidly than the deformation. Softening springs are such a kind of a springs in which the resistive force gets smaller as the spring deflection becomes larger [1].

# Nonlinearity in springs

## Applications of softening and hardening characteristic



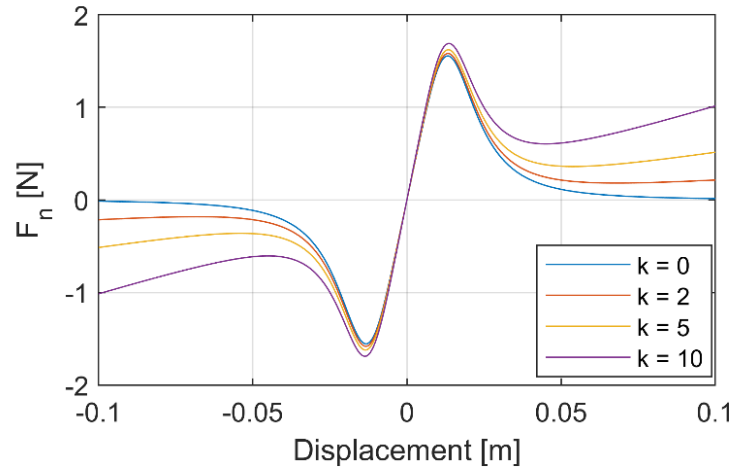
# Combined stiffness



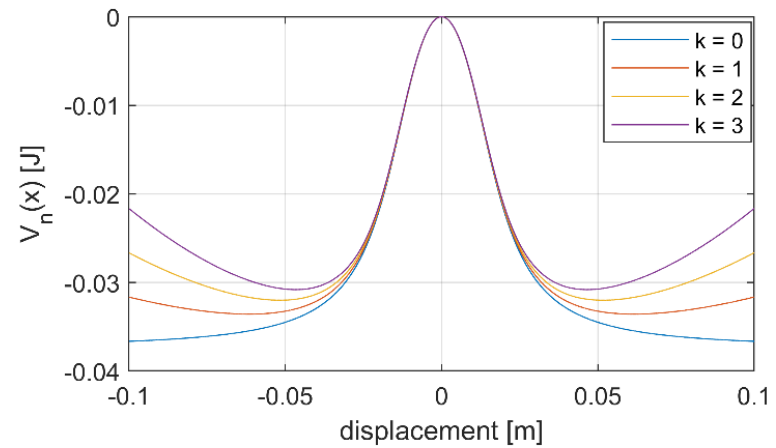
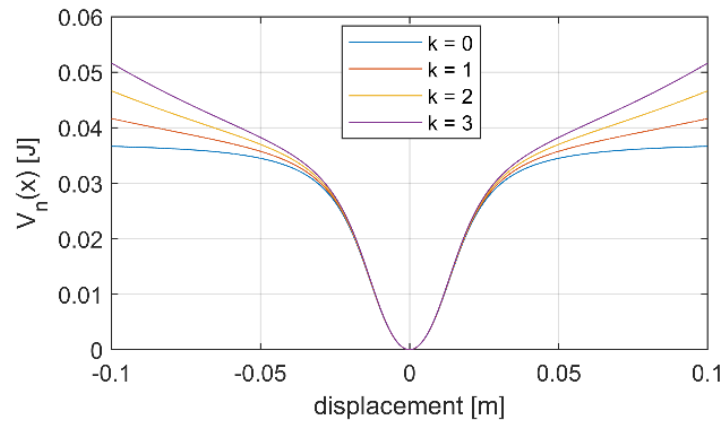
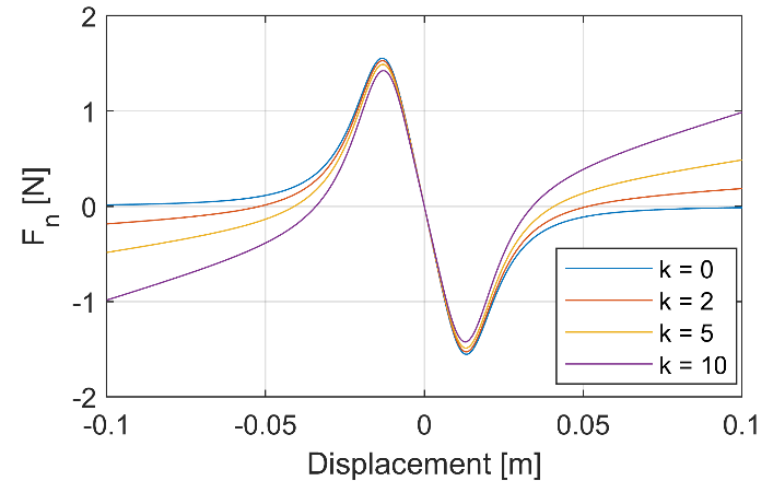
$$F_n(x) = kx + \frac{Ipq^3}{q^4 + x^4} \cdot x$$

# Combined stiffness

$I = 1 \text{ A}$



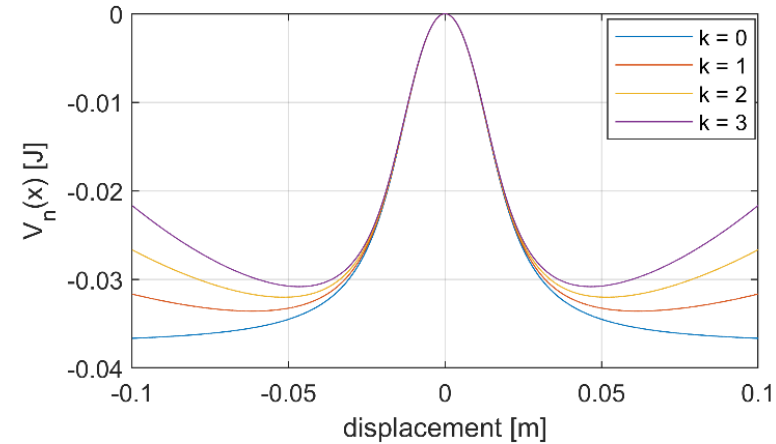
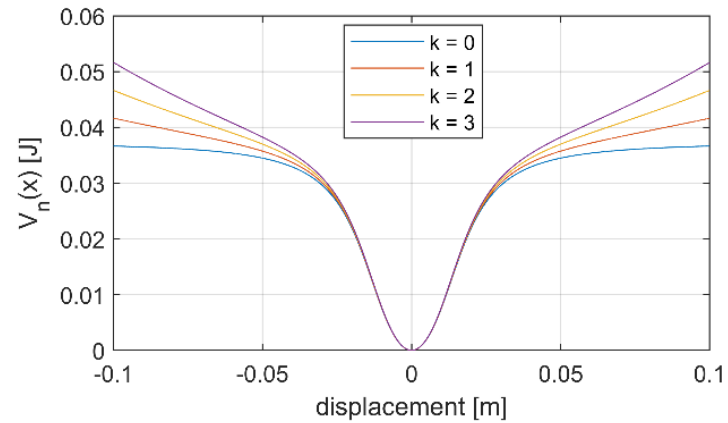
$I = -1 \text{ A}$





# Combined stiffness

## Equilibrium position

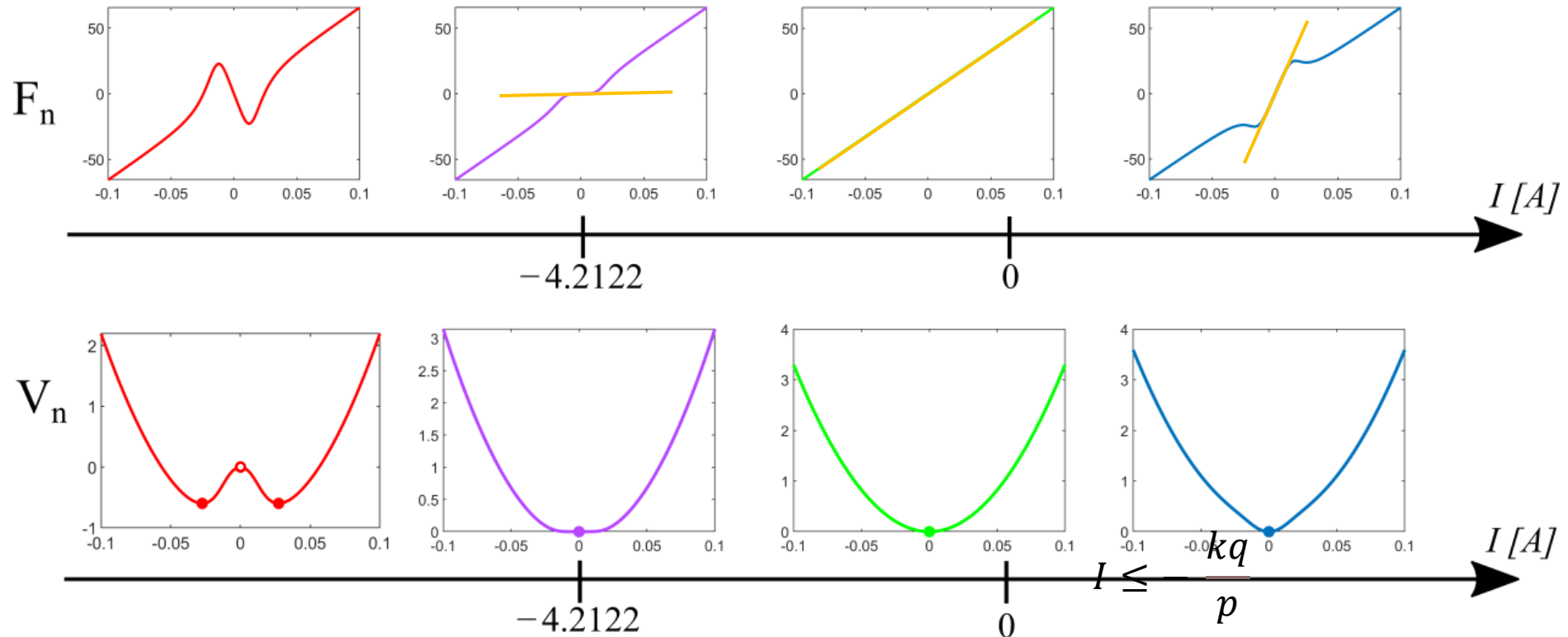


$$\begin{cases} \dot{x}_1 = 0 \\ -\frac{k}{m_1}x_1 - \frac{Ipq^3}{m_1(q^4 + x_1^4)} \cdot x_1 = 0 \end{cases}$$

$$x_1 = 0 \quad \vee \quad x_1 = \pm \sqrt[4]{\frac{-kq^4 - Ipq^3}{k}}$$

$$I \leq -\frac{kq}{p}$$

# Combined stiffness



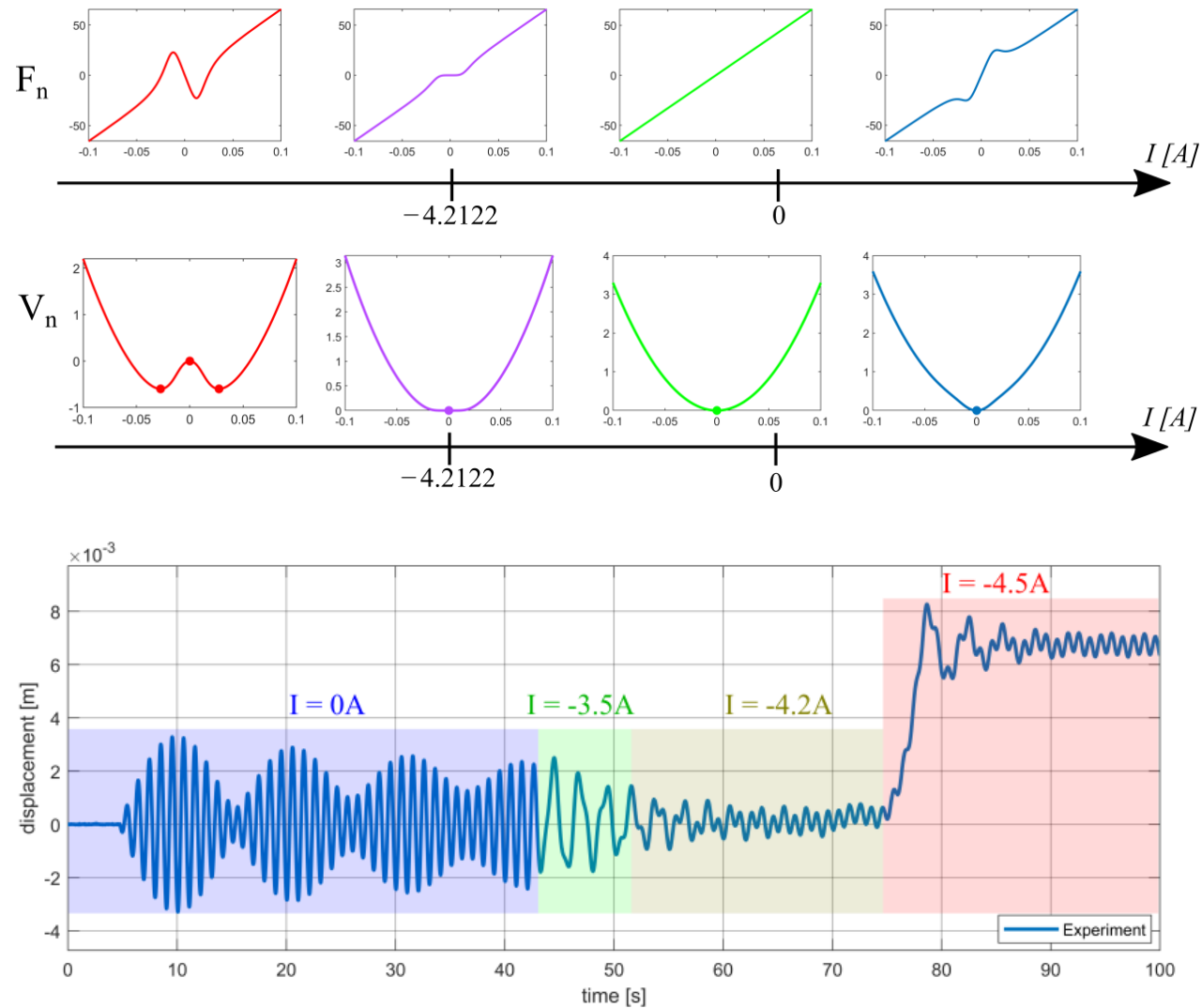
$$k = 659.5 \frac{N}{m}$$

$$p = 2.729 \frac{N}{A}$$

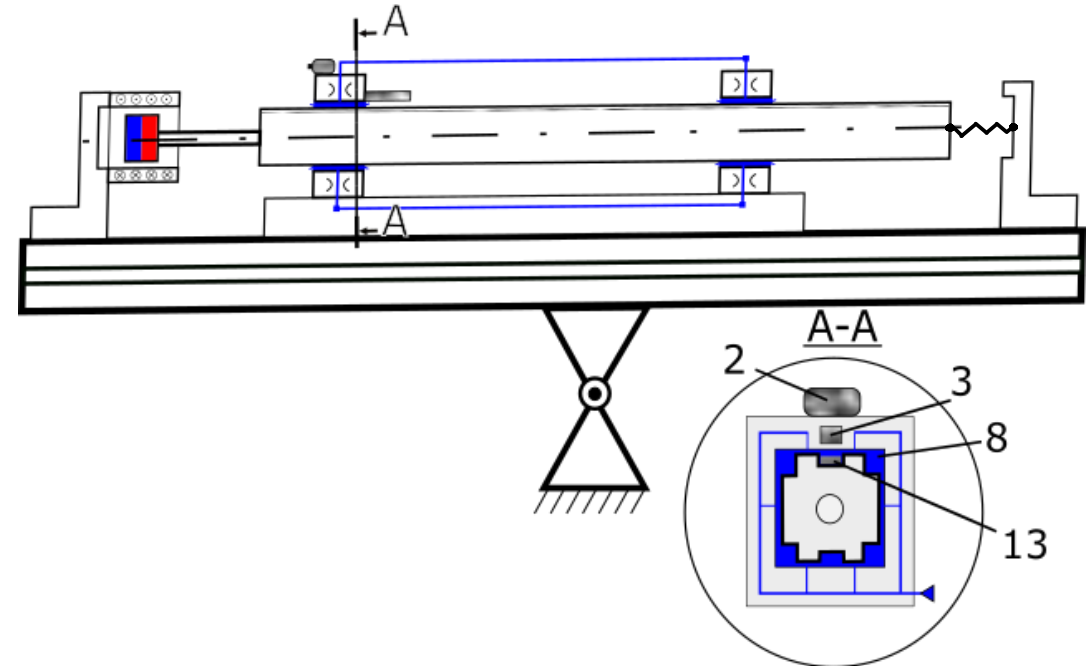
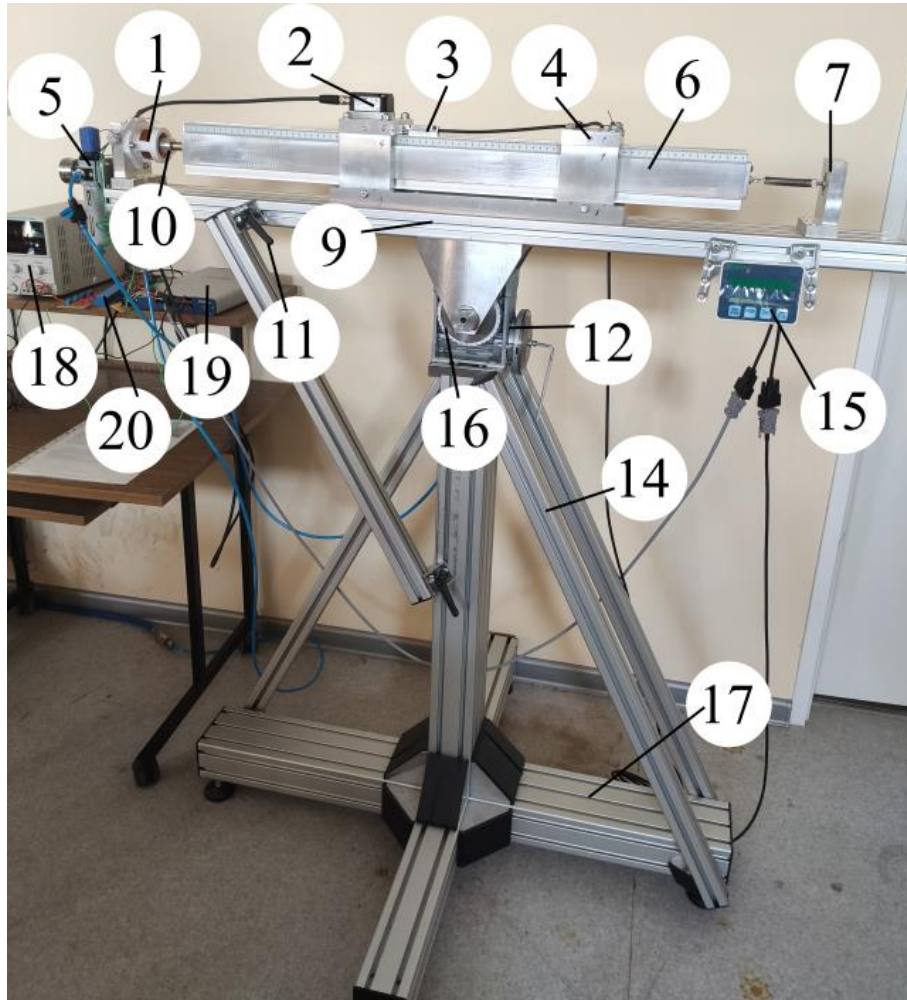
$$q = 0.01743 m$$

$$I = -4.2122 [A]$$

# Combined stiffness

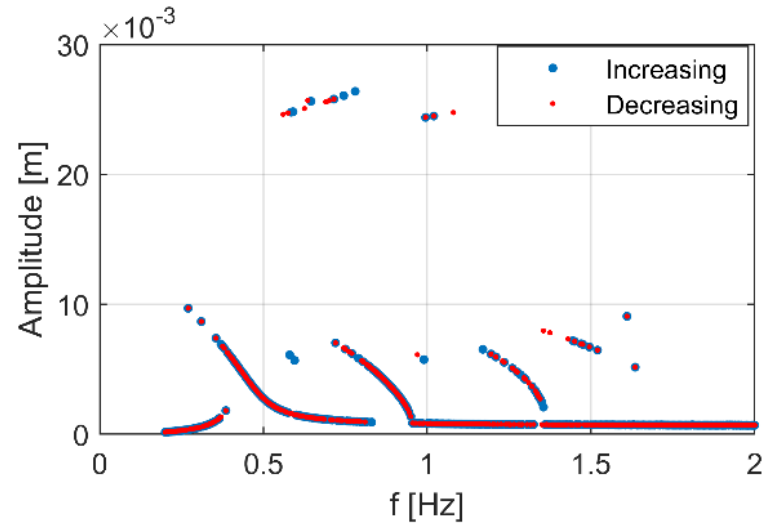
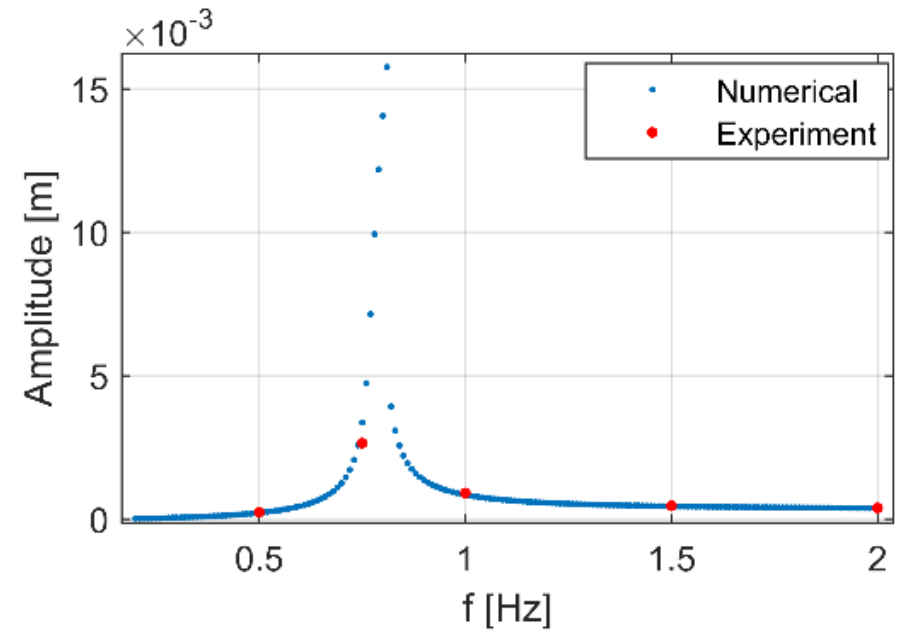
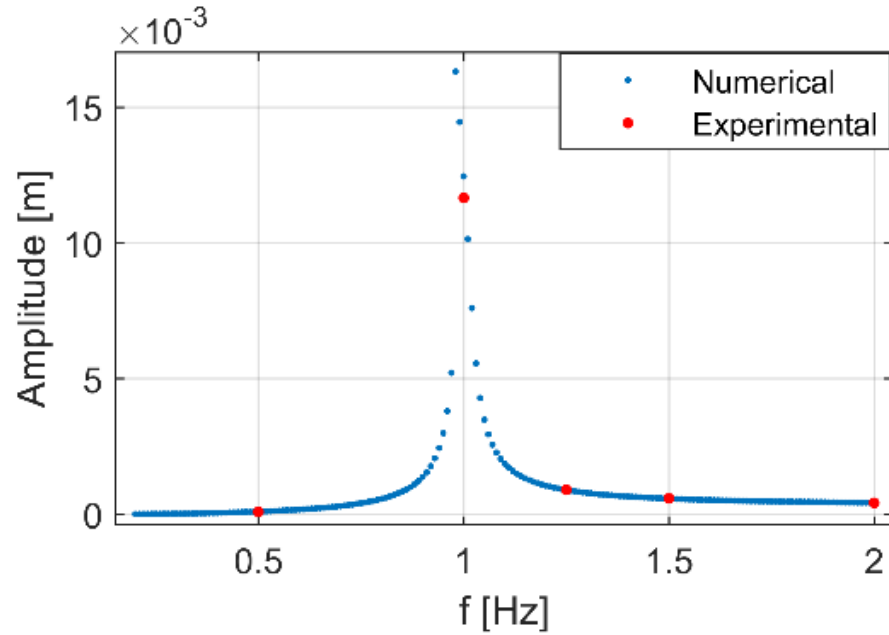


# Experimental rig



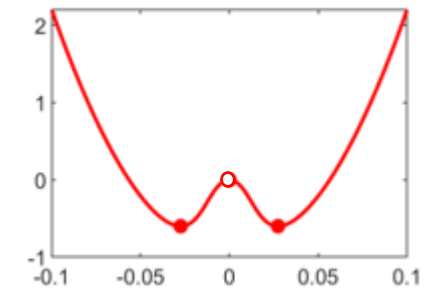
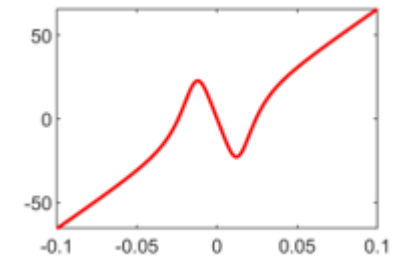
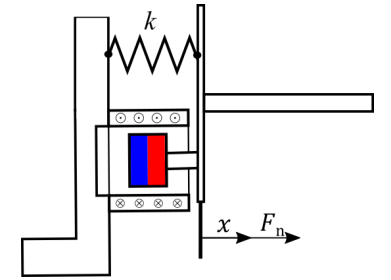
1 - coil, 2 - inclinometer, 3 - position sensor, 4 - aerostatic supports, 5 - air preparation system, 6 - slider, 7 - brackets, 8 - compressed air, 9 - base , 10 - magnet, 11 - angle adjustment locks , 12 - worm gear, 13 - magnetic ruler, 14 - supports, 15 - displacement display, 16 - angular scale, 17 - rig frame, 18 - power supply, 19 - data acquisition card, 20 - H-bridge.

# Frequency response



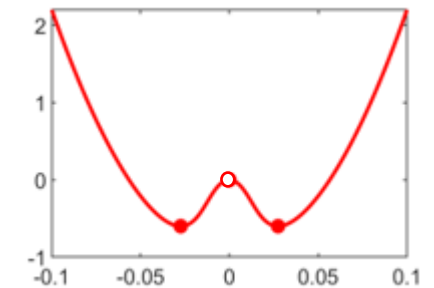
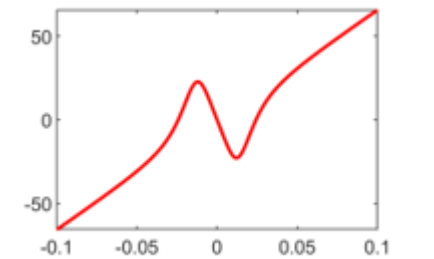
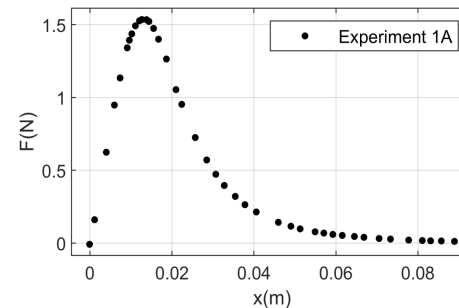
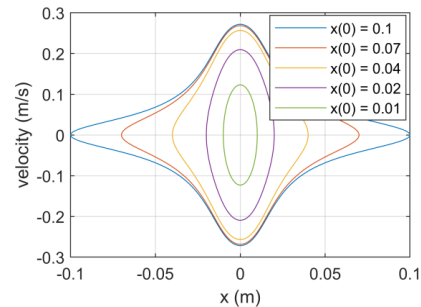
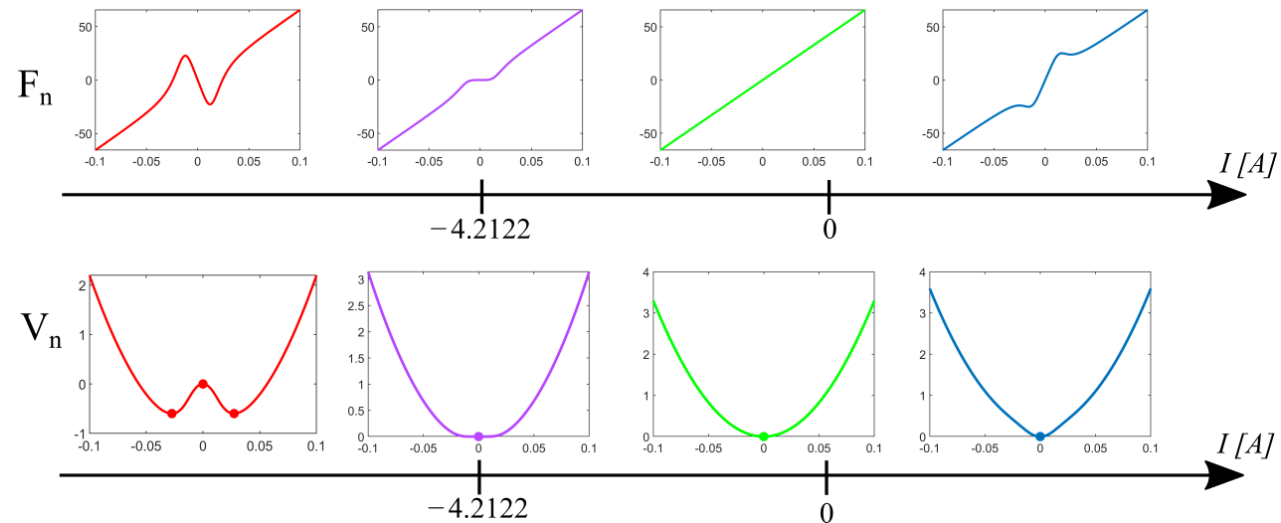
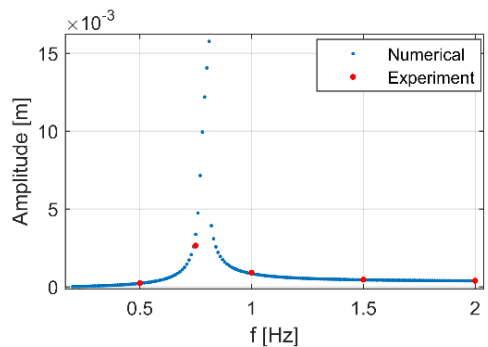
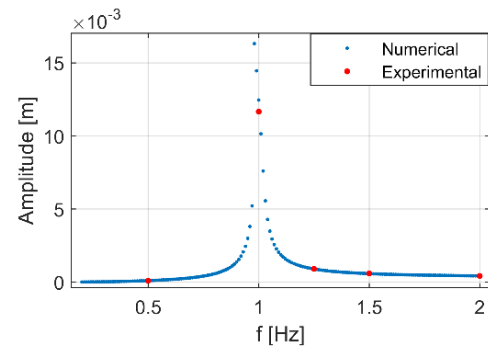
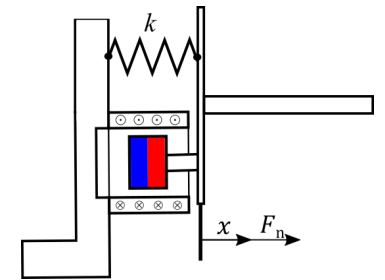
# Concluding remarks

- Electromagnetic spring force has been modeled and validated experimentally
- Spring of combined stiffness can produce softening, hardening, linear and bistable stiffness
- The spring can reproduce stiffness similar to Duffing stiffness  $F_d = \alpha x + \beta x^3$



# Thank you for your attention

- Spring of combined stiffness can produce softening, hardening, linear and bistable stiffness
- The spring can reproduce stiffness similar to Duffing stiffness



# Extention of the presentation

$$m_1 \ddot{x}_1 = -F_k(x_1) - F_e(x_1) - F_{c3}(\dot{x}_1) + F_h(t)$$

$$m_1 \ddot{x}_1 = -kx_1 - \frac{Ipq^3}{q^4 + x_1^4} \cdot x_1 - c_{c1}\dot{x}_1 + c_{c2}\dot{x}_1^3 + c_{c3}\text{sgn}(\dot{x}_1) + 2m_u r \omega^2 \sin(\omega t)$$

